

ADJUSTABLE

shock absorbers



Find out our
key products



Solution for most applications



Easy and intuitive choice



Excellent value for money



Wide availability



Fast delivery



Characteristics

Series of adjustable hydraulic shock absorbers de-energising the impact on the rod by the displacement of oil from one chamber to another. This displacement is controlled by a valve and a throttling mechanism according to the adjustment brought in. The adjustment is carried out by a nut set in the rear end. The adjusting field is from 0 to 9 and the nut is provided with a stopper grub screw. The optimal cushion is obtained moving the nut towards 9 if the cushion is too high at the beginning of the stroke; while moving the nut towards 0 if the cushion is too high near the end of the stroke. The best choice of the shock absorber could be done easily following the instructions on the side page. Supplied as standard in compliance with Reach and RoHS directives.



Type DR

from page 1.105.10



Adjustable hydraulic shock absorbers without mechanical stop. Is recommended an external mechanical stopper at 0,5 - 1 mm, before the end of the stroke.

Type DRF

from page 1.105.10



Adjustable hydraulic shock absorbers with mechanical stopper included.

How to choose

1. Precisely determine the data of the problem, that is the calculation factors m , v , F , x , s , in the table below.
2. Calculate the kinetic energy of the mass:

$$W_1 = 0,5 \cdot m \cdot v_2 \text{ (Nm)}$$
 Choose a cushioning with a capacity per cycle higher than the calculated value. The cushion length chosen must be used at point 3).
3. If there is an external motion force (hydraulic or pneumatic cylinder, motor, gravity, etc.) calculate the work done:

$$W_2 = F \cdot s \text{ (Nm)}$$
4. Calculate the total energy that must be dissipated per cycle:

$$W_3 = W_1 + W_2 \text{ (Nm)}$$
 Check that the value obtained is within the capacity limits of the chosen cushioning. Otherwise you must consider a cushioning with higher cushion length or diameter and in case calculate W_2 and W_3 again.
 It can be necessary to compare cushionings with different cushion lengths and calculate again each time.
5. It is better to choose a cushioning with a capacity 25 per cent higher than the required one in order to:
 - a) let following possible increases of the impact energy;
 - b) Work with safe margins when velocities are not easily valuable;
 - c) make sure that the cushioning lasts long, especially when working in dusty or contaminated environments.

6. Calculate the efficiency measurement:

$$ME = \frac{W_3 \cdot 2}{V_2} \text{ (Kg)}$$

Check that the value obtained is within the limits indicated for the chosen cushioning and this to get a linear and progressive cushion.

7. Were the "ME" out of the limits, you should choose a cushioning with a different capacity of efficiency measurement.
8. Varying the cushion length you can change the "ME"; however, at each variation of the cushion length you must remember to calculate the propelling energy of the point 3 again.
 Check whether the cushioning is condition to dissipate the energy generated by work frequency per hour into heat:

$$W_4 = W_3 \cdot X \text{ (Nm/h)}$$
9. Were the cushioning not in condition to dissipate it, you should choose among:
 - a) use of a cushioning with a higher capacity per hour taking care of calculating the point 3 again (were the cushion length different);
 - b) Use of a system with recirculation or external air/oil tank, both characterised by a higher capacity per hour;
 - c) cooling of the cushioning by air blow or another refrigerating fluid.

Factors

Symbol

W1	= Kinetic energy per cycle	(Nm)
W2	= Motion energy per cycle	(Nm)
W3	= Total energy per cycle	(Nm)
W4	= Total energy per hour	(Nm/h)
F	= Motion force	(N)
x	= Number of cycles per hour	(1/h)
s	= Cushioning length	(m)
v	= Mass speed	(m/s)
m	= Cushioned mass	(Kg)
ME	= Efficiency measurement	(Kg)

The shock absorbers are selected according to their energy absorbing capacity. The capacity values identify both the mass that can be cushioned and the energy that can be absorbed per cycle and hour.
 So the required performances must be compared with the table of the cushionings capacities to make sure that the energy can be absorbed, converted into heat and dissipated in the atmosphere.

Energy

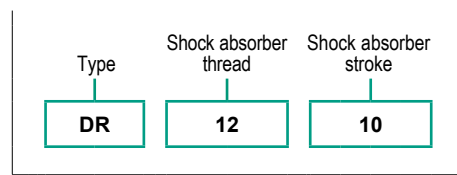
The factors that must be considered at the moment of selection are:

- Kinetic energy (W_1): it is the energy generated by the weight and the velocity of the mass that must be cushioned.
- Motion energy (W_2): it is the work, produced by the motion force acting on the mass that must be cushioned, multiplied by the cushion length.
- Total energy per cycle (W_3): it is the sum of the 2 preceding values and is the energy that must be dissipated every cycle.
- Total energy per hour (W_4): it is the product of the total energy per cycle by the number of cycles per hour; so it is the energy the cushioning must dissipate every hour.
- Efficiency measurement (**ME**): it is the mass (theoretical), which, without motion force and at the same velocity of the real mass, would have a kinetic energy equal to the total energy per cycle (W_3) of the real application. It is not the mass that must be cushioned; it doesn't indicate the power supported by the cushioning.

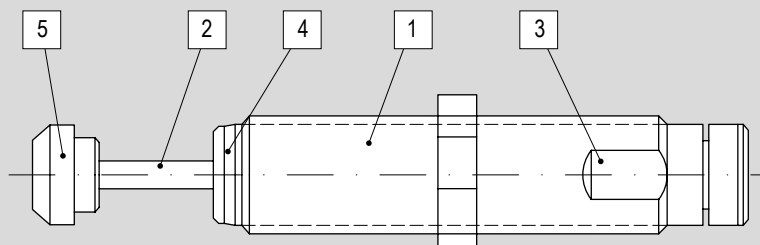
Code key

Type	Shock absorber thread	Shock absorber stroke
DR	12	10
<div style="border: 1px solid black; padding: 5px; margin-bottom: 5px;">DR</div> <div style="border: 1px solid black; padding: 5px;">DRF</div>	<div style="border: 1px solid black; padding: 5px; text-align: center;">10x1 ÷ 25x1,5</div>	<div style="border: 1px solid black; padding: 5px; text-align: center;">8 mm ÷ 40 mm</div>

How to order



Standard materials



Position	Description	Materiale
1	Body	Burnished steel
2	Rod	Stainless Steel
3	Spring	Steel
4	Seals	NBR - Polyurethane (PU) - Elastomer
5	Absorber	Polymer

Main features

8 ÷ 10

Strokes mm

DR

Type



12,5 ÷ 40

Strokes mm

DRF

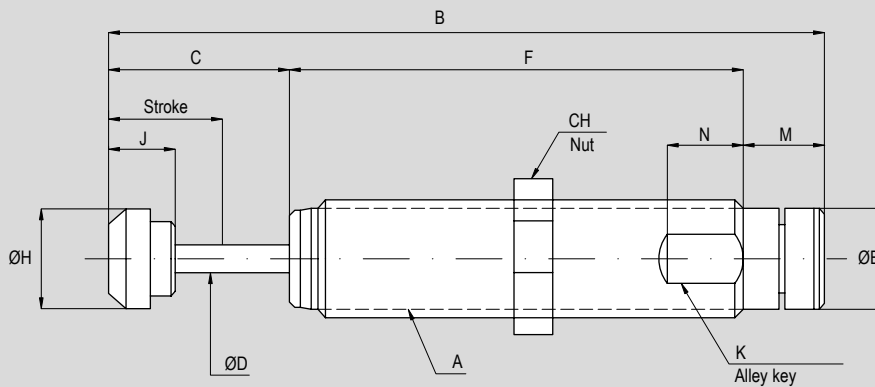
Type



Technical data

Type	DR	DRF
Description	Adjustable hydraulic shock absorbers without mechanical stopper	Adjustable hydraulic shock absorbers with mechanical stopper included
Temperature range	+5°C ÷ +70°C	+12°C ÷ +90°C
Strokes	8 - 10 mm	12,5 - 19,1 - 25,4 - 40 mm
Maximum impact speed	4 m/s	

Dimensions



Code	Item	Stroke	A (thread)	B	C	ØD	ØE	F	N	ØH	K	J	M	CH	Maximum absorbing capacity (Nm)		Efficiency measurement		Weight (g)
															Per cycle (W ₃)	Per hour (W ₄)	min. (Kg.)	max. (Kg.)	
041801	DR1008	8	10x1	66,5	14,5	2,5	8,8	40	-	6	-	6,5	12	13	1,8	3600	0,2	10	26
041802	DR1210	10	12x1	84	18	3,5	10,8	60	-	8	-	8	6	14	4	6000	0,9	57	43
041803	DRF1412	12,5	14x1,5	87	17,5	8	12	61	12	12	12	10	8,5	17	17	35000	0,6	90	60
041804	DRF2019	19,1	20x1,5	117,9	30	4,8	16,8	74,7	12,7	16,8	18	11	13,2	24	25	45000	2,3	226	130
041805	DRF2525	25,4	25x1,5	142,6	36,3	6,3	22,4	89,7	12,7	22,9	23	11	16,6	30	88	68000	9	1360	310
041806	DRF2540	40	25x1,5	189	51,1	6,3	22,4	121,3	12,7	22,9	23	11	16,6	30	100	90000	14	2040	400